

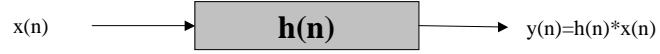
FIR Filters

Dr Yvan Petillot

Filters

- Filters are used to change the input signal in some way
 - ↳ Filter out unwanted signals
 - ↳ Enhance a good signal
 - ↳ Adjust the phase of a signal
 - ↳ Detect signal into noise

LTI systems



$$y(n) = \sum_{k=0}^{\infty} h(k)x(n-k)$$

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The Math

$$x[n] = e^{j\omega n} \rightarrow \boxed{h[n]} \rightarrow y[n] = x[n]*h[n] = e^{j\omega n}*h[n]$$

$$\begin{aligned} y[n] &= \sum_{k=-\infty}^{\infty} e^{j\omega(n-k)} h[k] \\ &= e^{j\omega n} \sum_{k=-\infty}^{\infty} e^{-j\omega k} h[k] \\ &= e^{j\omega n} H(e^{j\omega}) = e^{j\omega n} H(\omega) \quad H(e^{j\omega}) \equiv \sum_{k=-\infty}^{\infty} e^{-j\omega k} h[k] \end{aligned}$$

- $H(\omega)$ is the frequency response of the filter

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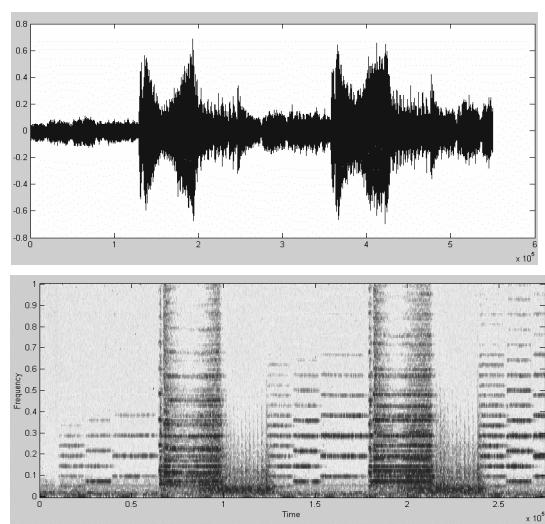
Frequency Response

$$\begin{aligned} H(\omega) &= H(e^{j\omega}) \equiv \sum_{k=-\infty}^{\infty} e^{-j\omega k} h[k] \\ &= H_{\text{Re}}(e^{j\omega}) + jH_{\text{Im}}(e^{j\omega}) \\ &= |H(e^{j\omega})| e^{j\phi_h(H(e^{j\omega}))} \end{aligned}$$

- $H(\omega)$ is the frequency response of the filter-another way to represent a system (impulse response)
 - ↳ Magnitude is called the frequency spectrum
 - ↳ Both magnitude and phase important in filter design

Frequency Spectrum

- Shows what frequencies are present in a signal
- Time signal shows sound intensity and some frequency
- Spectrogram shows which signals are present at a given time.



Eigenfunctions of a System

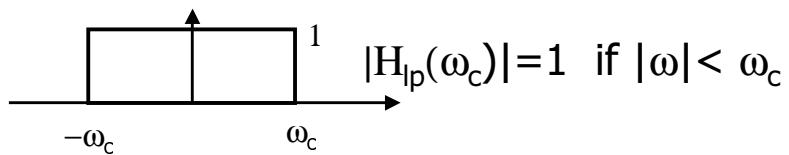
$$x[n] = e^{j\omega n} \longrightarrow h[n] \longrightarrow y[n] = e^{j\omega n} * h[n]$$

$$y[n] = e^{j\omega n} H(e^{j\omega}) = e^{j\omega n} H(\omega) \quad H(e^{j\omega}) \equiv \sum_{k=-\infty}^{\infty} e^{-j\omega k} h[k]$$

- Note: output has the same frequency as the input signal
- Special characteristic of an LTI system: sinusoid in gives an output at the same frequency => NO NEW FREQUENCIES
- LTI system changes phase and amplitude not frequency

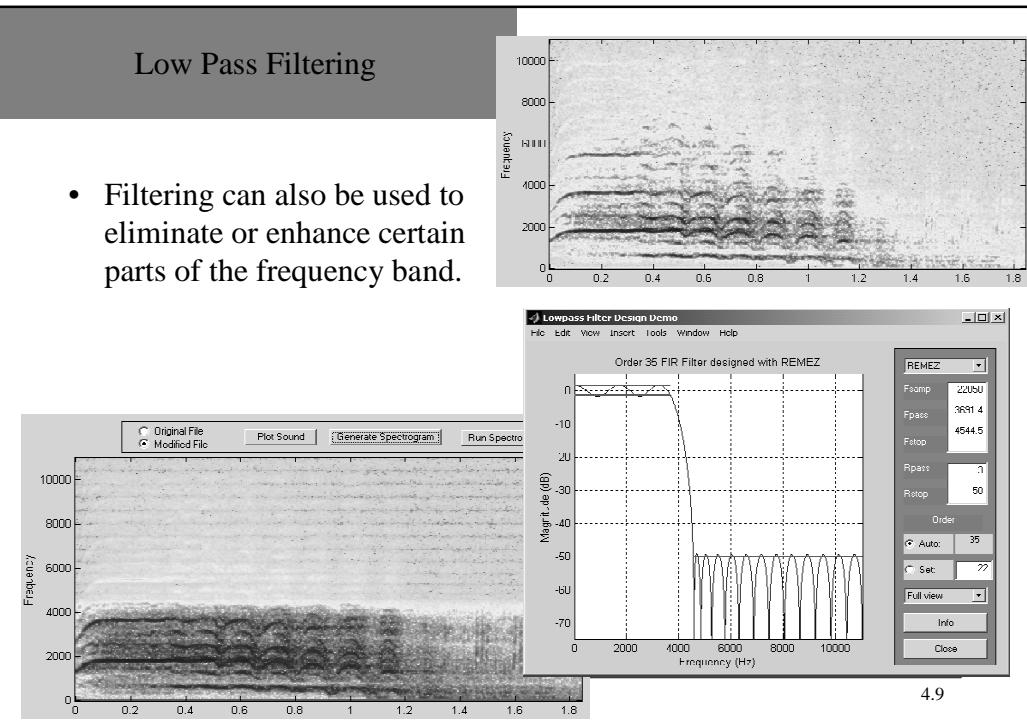
Ideal Filters

- Low-Pass Filters: Allow low frequencies to pass, blurs the signal



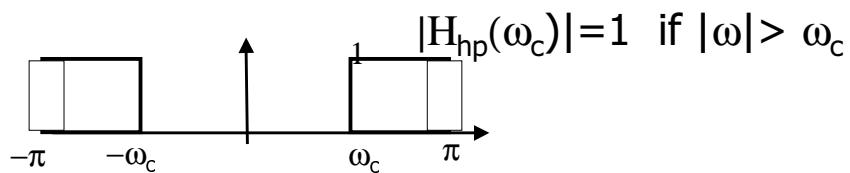
Low Pass Filtering

- Filtering can also be used to eliminate or enhance certain parts of the frequency band.



Other Ideal Filters

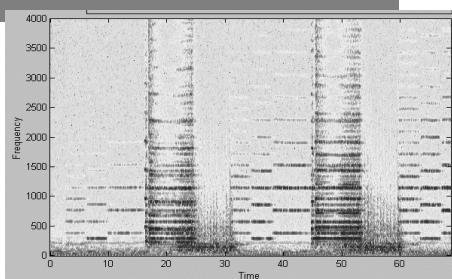
- High-Pass Filters: Allows high frequencies to pass, sharpens edges and fine details



- BandPass Filters: Allows selected frequencies to pass

High Pass Filtering Example

- Keeps all high sounds
- Eliminates low sounds



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Notes on Ideal Filters

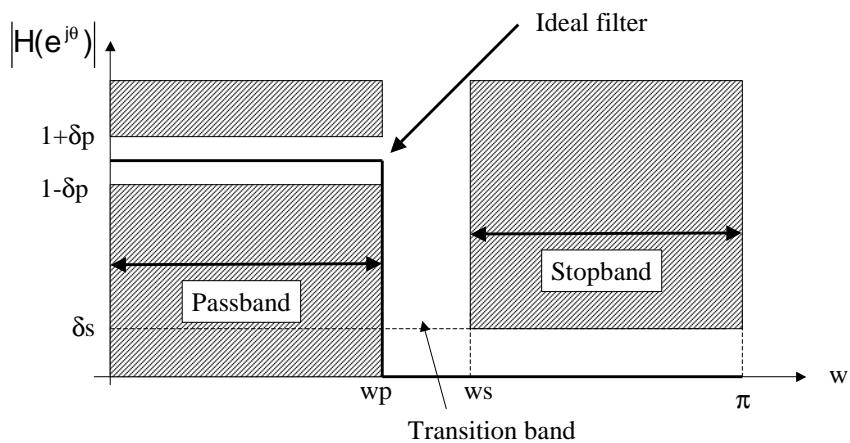
- These filters cannot be built in real-life due to the time-frequency duality problem
 - ↳ If a signal is time-limited, then it must be infinite in frequency
 - ↳ If a signal is frequency-limited, then it must be infinite in time

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FIR filters

Specification from ideal filters



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The Discrete-Time Fourier Transform (DTFT)

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{jn\omega} d\omega \quad X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-jn\omega}$$

- The first equation asserts that we can represent any time function $x[n]$ by a linear combination of complex exponentials

$$e^{j\omega n} = \cos(\omega n) + j \sin(\omega n)$$

- The second equation tells us how to compute the complex weighting factors $X(e^{j\omega})$
- In going from the DTFT to the ZT we replace $e^{j\omega n}$ by z^n

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FIR Filters:

$$H(e^{j\theta}) = \sum_{n=0}^{N-1} h(n) e^{-jn\theta} \quad H(z) = \sum_{n=0}^{N-1} h(n) z^{-n}$$

We know $H(e^{j\theta})$

How do we find $h(n)$?

$$h[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{jn\omega} d\omega$$

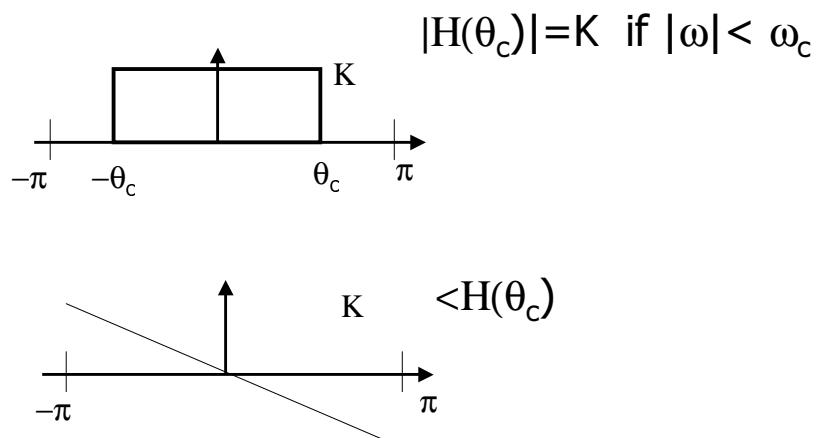
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How to find $h(n)$ for sampled signals ?

$$H(e^{jwT_s}) = \sum_{n=0}^{N-1} h(nT_s) e^{-jn w T_s}$$

$$h[nT_s] = \frac{1}{W_s} \int_{-\frac{W_s}{2}}^{\frac{W_s}{2}} H(e^{jwT_s}) e^{jn w T_s} dw \quad W_s = 2\pi f_s$$

Low Pass design



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Low Pass design

$$\begin{aligned}
 h_{lp}[n] &= \frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\theta}) e^{jn\theta} d\theta \\
 &= \frac{1}{2\pi} \int_{-\theta_c}^{\theta_c} K e^{jn\theta} d\theta = \frac{K}{2\pi} \left[\frac{e^{jn\theta}}{jn} \right]_{-\theta_c}^{\theta_c} \\
 &= \frac{K}{n\pi} \sin(n\theta_c)
 \end{aligned}$$

Infinite number of coefficients, non causal!

$$y(n) = \sum_{k=-\infty}^{\infty} h(k) x(n-k)$$

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Low Pass design

Solution: Take only a first N coefficients

$$y(n) = \sum_{k=-N}^N h(k)x(n-k)$$

Still non-causal!

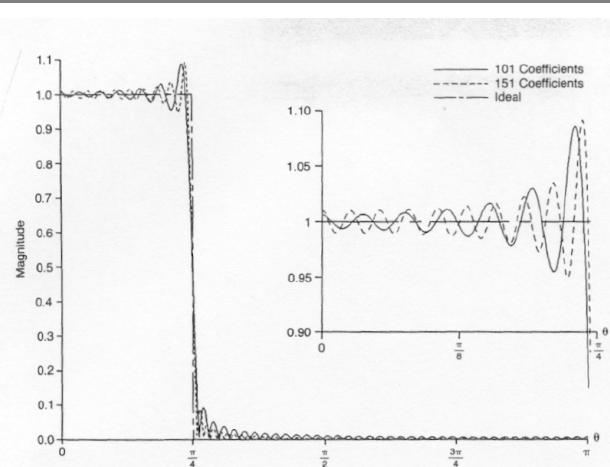
Shift them using a linear phase term!

$$H(e^{j\theta}) = K e^{-jN\theta}$$

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Low Pass design

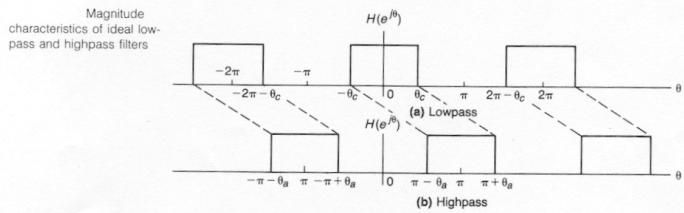


Lowpass filter frequency response for 101- and 151-coefficient designs

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Low Pass / High Pass Filter

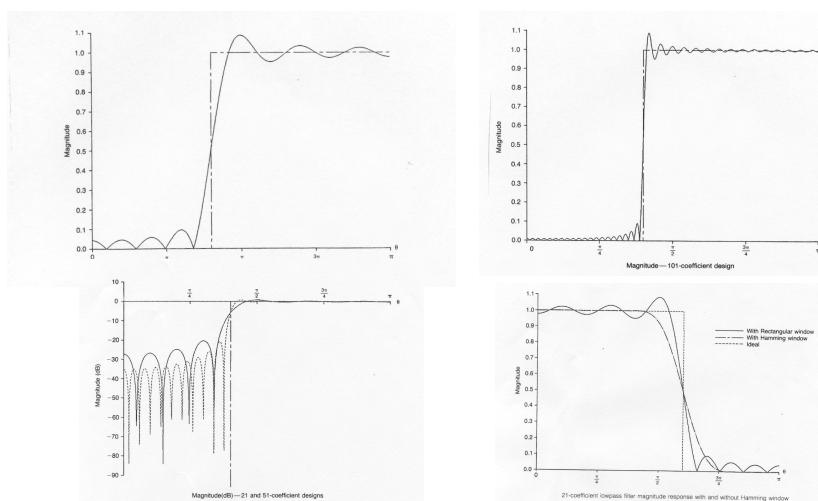


$$\begin{aligned}
 H_{hp}(e^{j\theta}) &= \sum_{n=0}^{N-1} h_{hp}(n) e^{-jn\theta} = H_{lp}(e^{j(\theta-\pi)}) \\
 &= \sum_{n=0}^{N-1} h_{lp}(n) e^{-jn(\theta-\pi)} = \sum_{n=0}^{N-1} h_{lp}(n) e^{-jn\theta} e^{jn\pi} \quad h_{hp}(n) = h_{lp}(n) (-1)^n \\
 &= \sum_{n=0}^{N-1} h_{lp}(n) (-1)^n e^{-jn\theta}
 \end{aligned}$$

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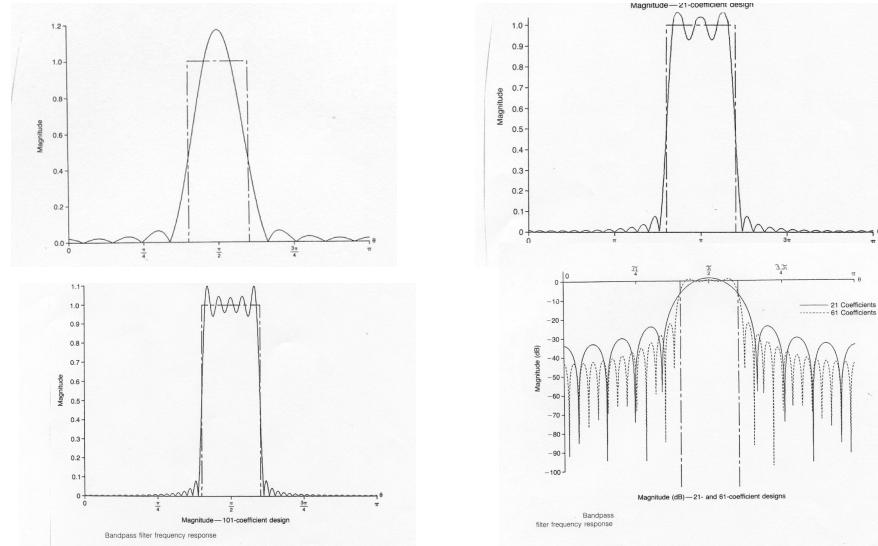
High Pass Filter



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Band Pass design



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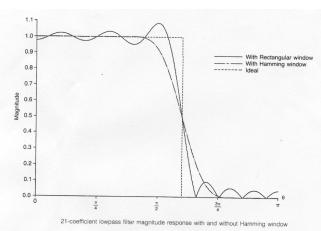
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Gibbs Phenomenon

Finite number of coefficients:

$$\hat{h}[n] = h(n) \cdot w(n) \quad w(n) \text{ windowing function}$$

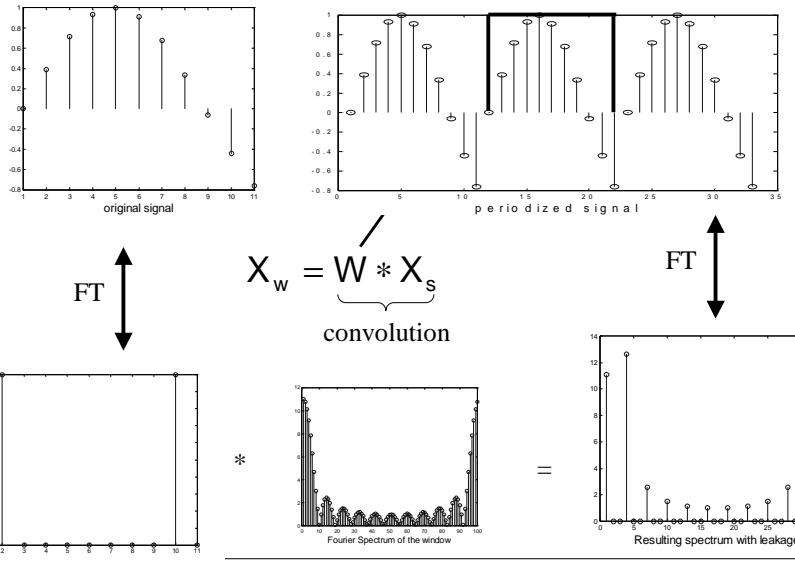
Same problem as for spectrum analysis!



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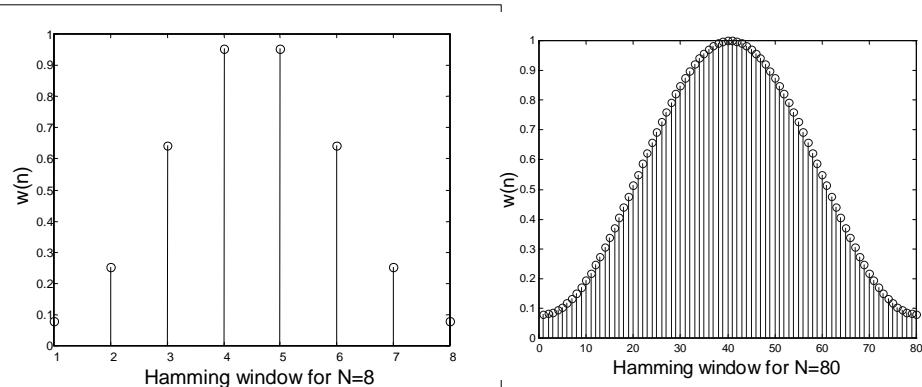
Square window



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Optimised classical windows

$$\underline{\text{Hamming:}} \quad w(n) = 0.54 - 0.46 * \cos\left(\frac{2\pi n}{N-1}\right)$$

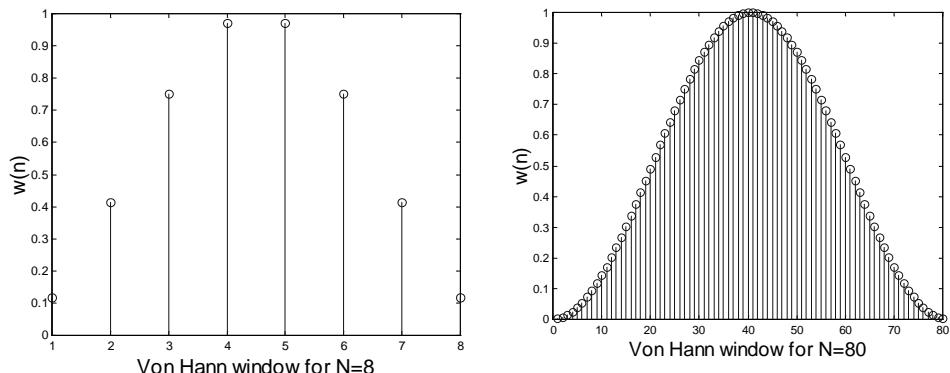


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Optimised classical windows

Hanning: $w(n) = 0.50 - 0.50 * \cos\left(\frac{2\pi n}{N-1}\right)$

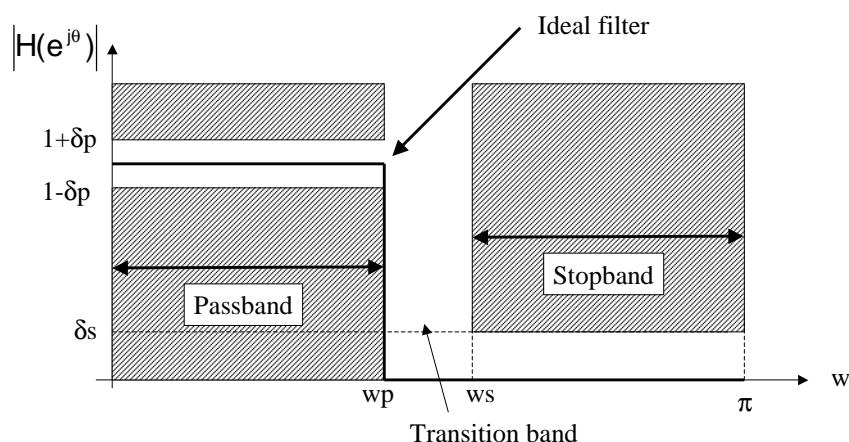


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FIR filters

Specification from ideal filters



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Optimised classical windows

Difference between windows ?

Window type	Mathematical expression	Sidelobes (dB)	Transition width	Stop band attenuation
Rectangular	$w(n) = 1, \quad 0 \leq n \leq N - 1$	-13	$0.9/N$	-21
Hamming	$w(n) = 0.54 - 0.46 \cos\left(\frac{2\pi n}{N-1}\right) \quad 0 \leq n \leq N - 1$	-31	$3.1/N$	-44
Hanning	$w(n) = 0.50 - 0.40 \cos\left(\frac{2\pi n}{N-1}\right) \quad 0 \leq n \leq N - 1$	-41	$3.3/N$	-53
Blackman	$w(n) = 0.42 - 0.50 \cos\left(\frac{2\pi n}{N-1}\right) + 0.08 \cos\left(\frac{4\pi n}{N-1}\right) \quad 0 \leq n \leq N - 1$	-57	$5.5/N$	-74